SOME MODIFICATIONS of the WEISS–STAFFANS PERTURBATION THEOREM

Piotr Grabowski

INSTITUTE OF CONTROL AND BIOMEDICAL ENGINEERING

AGH UNIVERSITY OF SCIENCE AND TECHNOLOGY

Kraków, Poland

pgrab@agh.edu.pl

home.agh.edu.pl/~pgrab/main.xml



AFA Seminar, 18 and 25 March, 2015; FAM, AGH UST

Last modification: February 6, 2015 ©Submitted to: JNRC February 18, 2015 as paper RNC-15-0087

1

Abstract

For boundary control systems in factor form a version of the Weiss perturbation result is derived and formulated as an exponential stability robustness result (Theorem 3.1). An example of a heating rod control, illustrating its application is given.

Next a generalization of the Weiss perturbation to a class of retarded systems of the neutral type is presented (Theorem 4.1). The characteristic feature of this generalization is that it allows to deal with a dynamic perturbation rather than a static one. Using this result we get a new derivation of an exponential stability criterion.

We also show that some parabolic systems without the admissibility of control operator still admit a weakened version of the Weiss perturbation result (Theorem 5.1). This result is a consequence of the maximal parabolic regularity and the Balakrishnan–Washburn estimates, and is illustrated in details by an example of an unloaded electric $\Re C$ -transmission line.